

*A Labelled Deduction System  
for Kanger's Deontic-  
Praxeological Logic*

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# Plan of paper "A LDS for KTR"

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- What kind of theory is Kanger's theory of rights?

- Set of implications.

- What kind of logic is adequate for it?

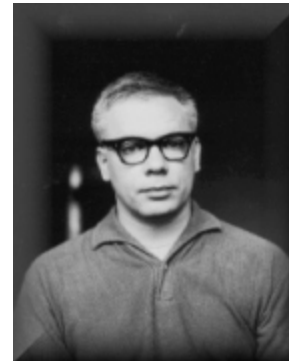
- Segerberg's criteria.

- How to assess adequacy of a logic for KTR?

- Proof strategy.

- Can a labelled deduction system be adequate for KTR?

- Yes.



Stig Kanger (1924-1988)

# References

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## Kanger's theory of rights

- Kanger, Stig (1972) Law and Logic. *Theoria* **38** : 105-129.
- Kanger, Stig (1966) Rights and Parliamentarianism. *Theoria* **32** : 85-115.

## Reprinted in:



G. Holmström-Hintikka, S. Lindström and R. Sliwinski (eds.) *Collected Papers of Stig Kanger with Essays on his Life and Work*, Vols. I-II. Kluwer Academic Publishers, 2000.

## Criteria of adequacy

- Segerberg, Krister (1992) Getting Started: Beginnings in the Logic of Action. *Studia Logica*, **51**: 347-378.

## Action semantics

- Hilpinen, Risto. (1997) On Action and Agency. In: E. Ejerhed and S. Lindström (eds.), *Logic, Action and Cognition – Essays in Philosophical Logic*, pp. 3-27. Kluwer Academic Publishers

## Labelled deduction systems

- Basin, David, Matthews, Seán and Viganò, Luca (1998) Natural Deduction for Non-Classical Logics. *Studia Logica* **60**:119-160

# *Kanger's theory of rights*

“Strength diagram”

# Some history: Wesley Newcomb Hohfeld

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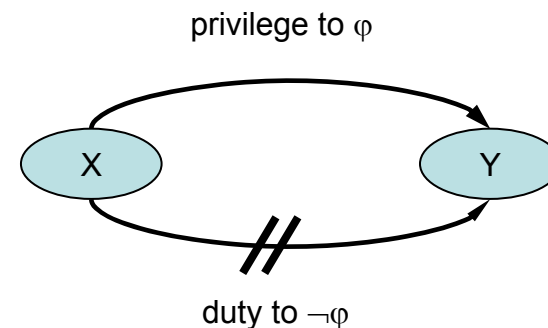
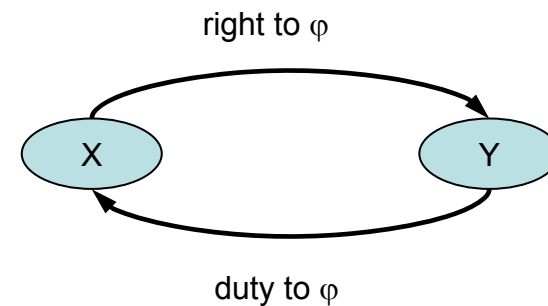
- Seminal paper on logic of rights: (1913) Some Fundamental Legal Conceptions as Applied in Judicial Reasoning. I. *Yale Law Journal* **23**: 16-59.

Jural Opposites	{ right no-right	privilege duty	power disability	immunity liability
Jural Correlatives	{ right duty	privilege no-right	power liability	immunity disability

# Hohfeldian classification

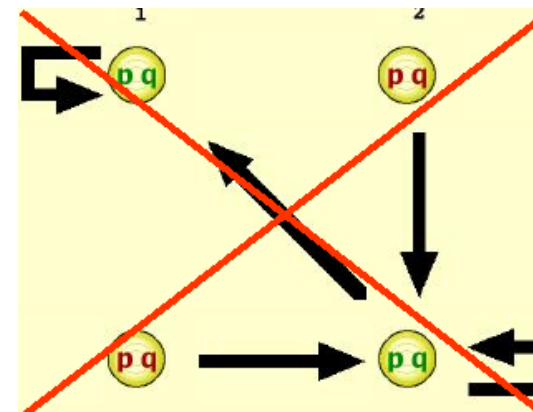
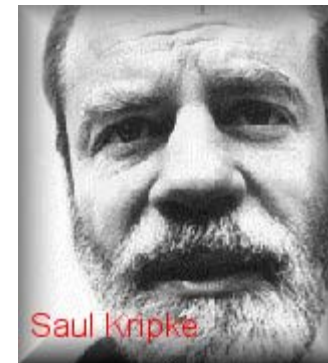
- Interdefinability:

- Correlatives as a kind of converse relations:  
 $\text{RightTo}[\varphi](X, Y)$  iff  $\text{DutyTo}[\varphi](Y, X)$ .
- Opposites as similar to “complement” relation:  
 $\text{PrivilegeTo}[\varphi](X, Y)$  iff  $\neg \text{DutyTo}[\neg\varphi](X, Y)$ .



# Modal logic and theory of rights

- Stig Kanger.
  - Regarded his theory of rights as one of his substantial contributions to philosophy.
  - Worked on it intermittently for thirty years.
  - Methods of modal logic.
- Interesting fact:
  - Kanger and Kripke independently invented semantics of “possible worlds with accessibility relations”.
  - But in KTR Kanger used only axiomatic (not formal semantic) methods.
    - Explanation: the semantics of rights involves the semantics of action, which he was trying to develop.



# Active and passive rights

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- Hohfeld-Kanger notion of right.
  - There are eight types of “simple” rights.
  - Right is a relation between: Two agents,
    - Bearer and Counterparty
  - w.r.t. Action,
    - s. t. one of two agents has duty or permission to execute or to omit the action (which is the “object-matter” of the right).
  - In accordance with traditional distinction between:
    - “Passive rights”, right to have something done (Counterparty obligatives) and “Active rights”, right to do something (Bearer’s permissives).

COUNTERPARTY OBLIGATIVES

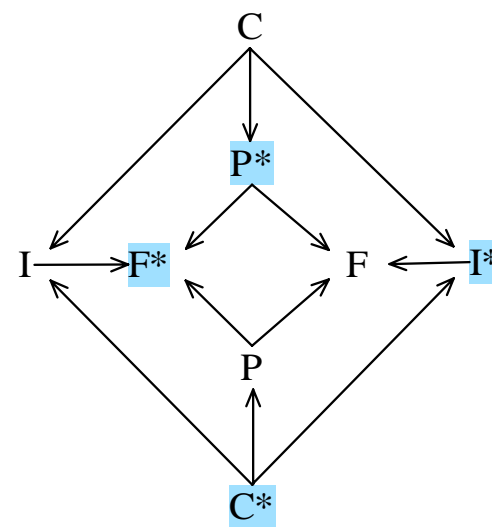
*Shall*  $\pm Do(y, \pm F)$

BEARER PERMISSIVES

$\neg$ *Shall*  $\pm Do(x, \pm F)$

# Looking inside the rights

- Two modal operators:
  - Deontic [Shall],
  - Praxeological [Do].
    - Historical remark:
      - Fitch, Frederic (1963) A Logical Analysis of Some Value Concepts. *The Journal of Symbolic Logic* **26**: 135-142
- Types of simple rights: P: [(Counter) Claim, (Counter) Immunity], A: [(Counter) Power, (Counter) Freedom].

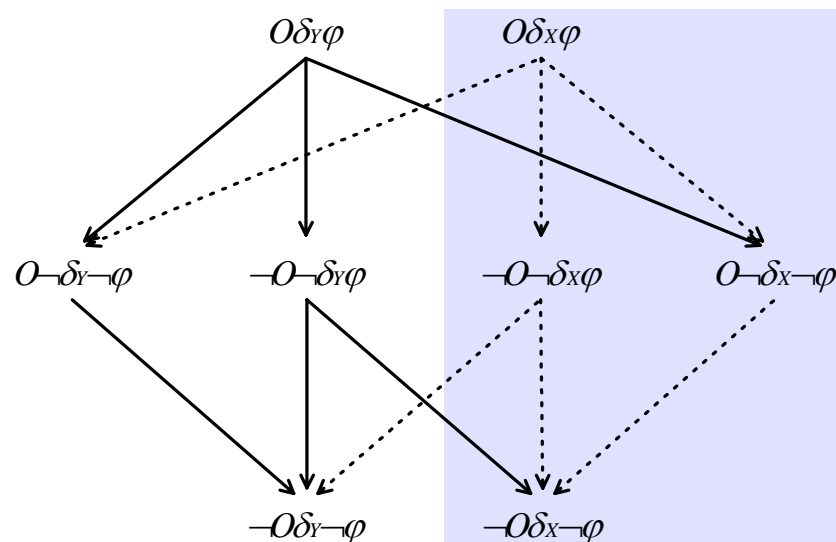
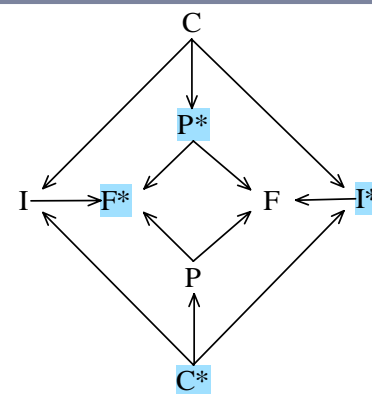


(X has a claim)  $O\delta_Y\varphi$

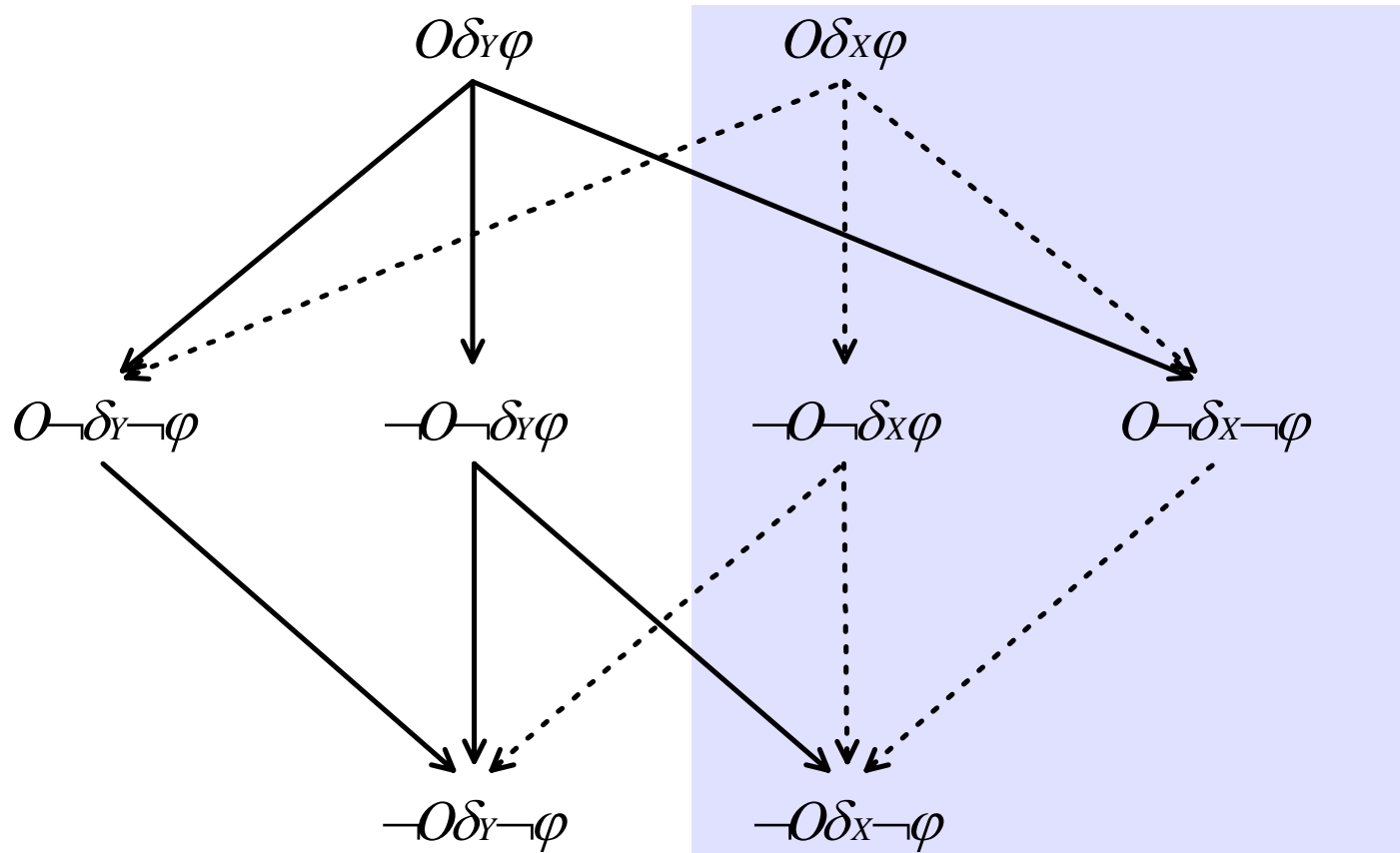
(X has a caounterclaim)  $O\delta_{Y-\varphi}$

# Strength diagram

- How to read it?
  - C implies  $P^*$  := 'X has a claim-right versus Y to the effect that  $\varphi$ ' implies 'Y has a power-right versus X to the effect that  $\varphi$ '.
- How to translate it to deontic-praxeological logic?
  - C implies  $P^*$  := 'It shall be that Y sees to it that  $\varphi$ ' implies 'Not: it shall be that not: Y sees to that  $\varphi$ ' .
    - More informal reading: If an action is obligatory, it is permitted.

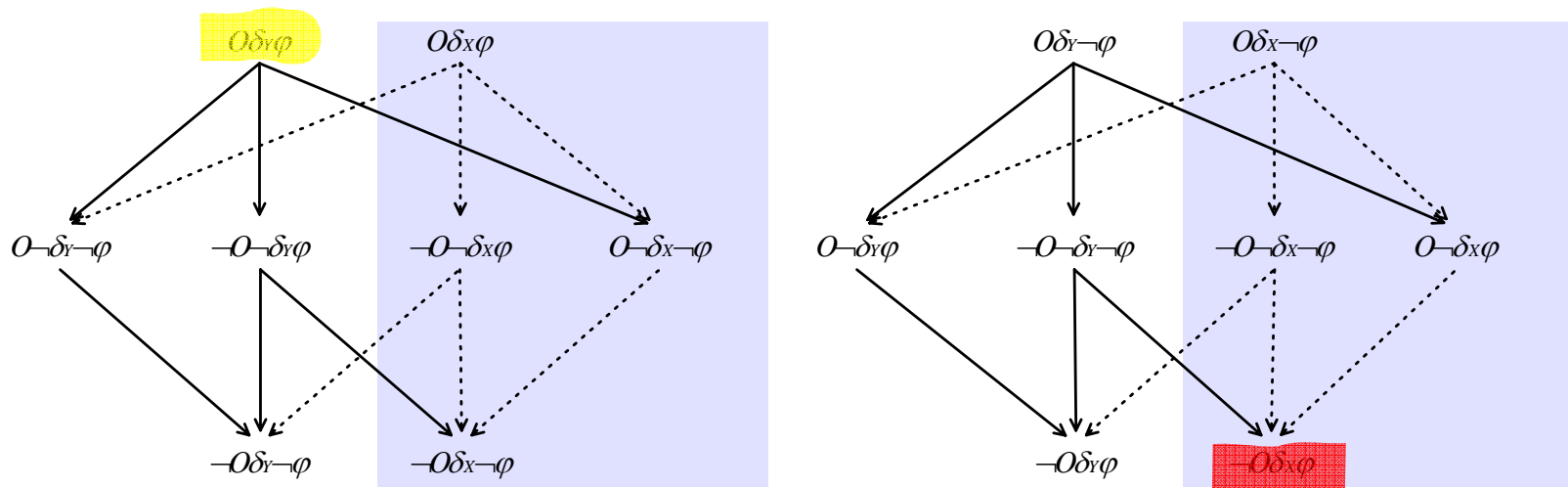


# Strength diagram: DP explication



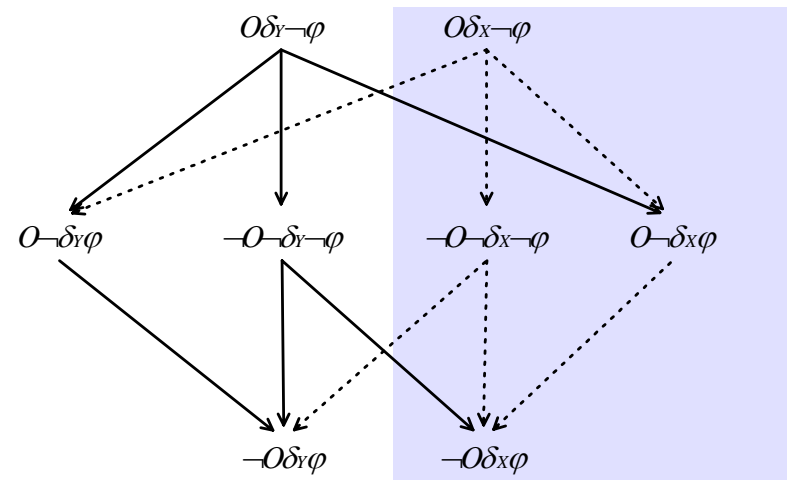
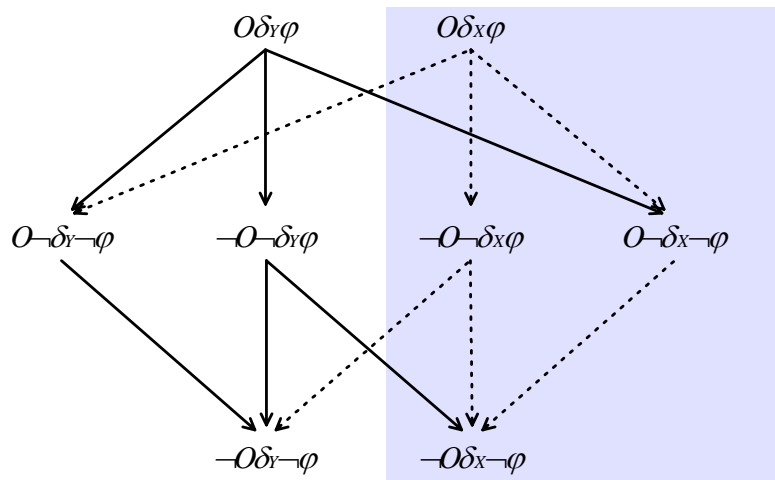
# Atomic rights: combination of affirmations and negations of simple rights [ar3]

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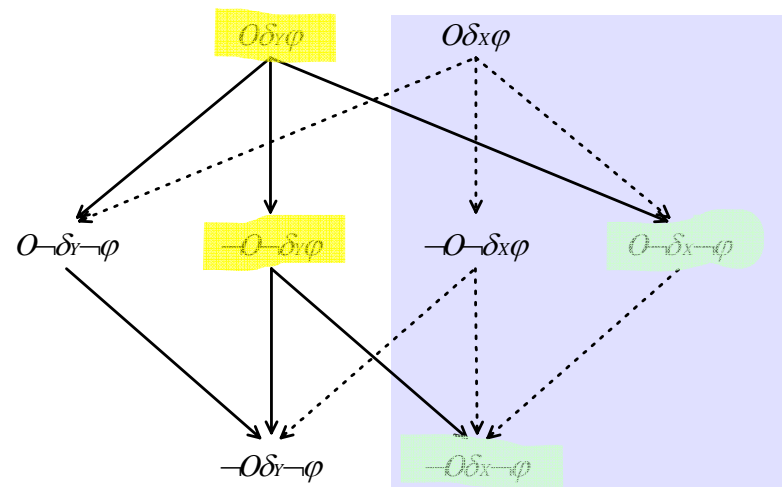
# Atomic rights: combination of affirmations and negations of simple rights

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# Two-agents deontic system

- Relations between deontic statuses of actions of two agents.
- Left side: agent Y. Right side: agent X.
- “Transversal” implications show: that if an action of one agent is obligatory, then the “opposite” action of another agent is forbidden (and she is not obliged to do it).



# What kind of theory is KTR?

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- Strength diagram shows in a maximal way necessary configurations of any logically viable normative system.
- What kind of logic would be adequate for KTR (i.e. “strength diagram”)?
  - The provability of SD-implications is not sufficient for adequacy.
  - No other deontic-praxeological implication should be provable.

$$RP^{imp} = \left\{ \begin{array}{l} C \Rightarrow I, C \Rightarrow P^*, C \Rightarrow I^*, P^* \Rightarrow F^*, P^* \Rightarrow F, \\ C^* \Rightarrow I^*, C^* \Rightarrow P, C^* \Rightarrow I, P \Rightarrow F, P \Rightarrow F^* \end{array} \right\}$$

Necessary condition of adequacy of logic  $\vdash_l$  for KTR:

If  $\varphi \in RP^{imp}$ , then  $\vdash_l \varphi$ .

# Seegerberg's criteria

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- “[...] Kanger himself does not tie his presentation to a unique underlying logic. Rather, he notes the conditions a logic must satisfy in order to fit his theory. [...] the logic must support the logical relationships portrayed in the diagrams [...] “That is to say,
- **the minimum condition** is that the logic must be strong enough to allow the derivation of logical implications in the diagram;
- and **the maximum condition** is that the logic must not be so strong that any new implications are added in those diagrams.”



*Construction of logic for KTR  
and  
applying Segerberg's criteria*

Tasks:

Constructing LDS and  
[minimum condition] proving provability, and  
[maximum condition] proving unprovability

## First step: defining KTR

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- We set that the relation of logical implication is reflexive and transitive.
- KTR is reflexive and transitive closure of  $RP^{imp}$  (i.e. implications depicted in the “strength diagram”).

For simple right types  $X, Y, Z$ ,  $KTR$  is the smallest set such that:

(i)  $RP^{imp} \subseteq KTR$ ,

(ii)  $X \Rightarrow X \in KTR$ ,

(iii) If  $X \Rightarrow Y \in KTR$  and  $Y \Rightarrow Z \in KTR$ , then  $X \Rightarrow Z$ .

## Second step: choosing a logic

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- Labelled deduction for normal propositional modal logics.
  - Approach developed by: Basin, Matthews, and Viganò.
- Modification of BMV approach:
  - Application to multimodal case.
  - Adjustment to “Fitch style” proofs.

# The basic ideas of BMV approach

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- The elimination and introduction rules for universal and existential modalities remain the same for different logics.
- The difference is established *via* “relational theory” which encodes the properties of the frames characterized by the logic in question.
  - Example: instead of  $D$  axiom we use assumption free rule  $R(w, f(w))$ , where  $f$  is Skolem function.
- The non-relational language is enriched with set of indices.
  - Syntax for non-relational sentences: [index] [colon] [unlabelled sentence].

## L-deduction rules for connectives

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- The sentences must have the same index (label) for a rule to be applicable.
- Example: conditional introduction [proof-to-proof rule] and conditional elimination [sentence(s)-to-sentence rule].
- Important exception: negation rule.

$\rightarrow$  *Intro*

$$\frac{\Gamma, w_i : \varphi \vdash w_i : \psi}{\Gamma \vdash w_i : \varphi \rightarrow \psi}$$

$\rightarrow$  *Elim*

$$w_i : \varphi \rightarrow \psi, w_i : \varphi \vdash w_i : \psi$$

## Global negation rule

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- Local negation is not strong enough.
- Intuitively: impossible world in a frame shows that the frame itself is not possible.

*$\neg$ Intro*

$$\frac{\Gamma, w_i : A \vdash w_j : \perp}{\Gamma \vdash w_i : \neg A}$$

# Rules for universal and existential modalities

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□ Intro

$$\frac{\Gamma, R(w_i, w_j) \vdash w_j : \psi}{\Gamma \vdash w_i : \Box \psi}$$

[ $w_j$  is new index]

□ Elim

$$R(w_i, w_j), w_i : \Box \varphi \vdash w_j : \varphi$$

◇ Intro

$$R(w_i, w_j), w_j : \varphi \vdash w_i : \Diamond \varphi$$

◇ Elim

$$\frac{\Gamma, R(w_i, w_j), w_j : \varphi \vdash w_k : \psi}{\Gamma, w_i : \Diamond \varphi \vdash w_k : \psi}$$

[ $w_j$  is new index]

## Geometry of meaning

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- Hypothesis: LDS open new modelling possibilities.
  - Example: irreflexive frames.
    - Uncharacterizable using “box/diamond” language.
    - Could be easily represented within relational theory.

# Choosing modalities

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- For  $O$  the choice seems obvious.
  - Universal modality.
  - Relational theory: seriality (D).
- For  $\delta$ ?
  - Universal modality.
  - Relational theory: reflexivity (T).
    - On the right side: Kanger's axiomatization from Rights and Parliamentarianism.

$$\frac{\vdash \varphi \rightarrow \psi}{\vdash O\varphi \rightarrow O\psi}$$
$$(O\varphi \wedge O\psi) \rightarrow O(\varphi \wedge \psi)$$
$$O\varphi \rightarrow \neg O\neg\varphi$$
$$\frac{\vdash \varphi \leftrightarrow \psi}{\vdash \delta\varphi \leftrightarrow \delta\psi}$$
$$\delta\varphi \rightarrow \varphi$$

# Rules for LDS for KTR

$\odot$  *Intro*

$$\left| \begin{array}{l} \left| \begin{array}{l} \text{k. } R_{\odot}(w_i, w_j) \\ \vdots \\ \text{l. } w_j : \varphi \end{array} \right. \\ \text{m. } w_i : \odot \varphi \quad \odot \text{ Intro: k-l} \end{array} \right.$$

[ $w_j$  is new index, may not appear outside its subproof]

$\odot$  *Elim*

$$\left| \begin{array}{l} \text{k. } R_{\odot}(w_i, w_j) \\ \vdots \\ \text{l. } w_i : \odot \varphi \\ \vdots \\ \text{m. } w_j : \varphi \quad \odot \text{ Elim: k,l} \end{array} \right.$$

$\odot$  *seriality*

$$\left| \begin{array}{l} \vdots \\ \text{k. } R_{\odot}(w_i, f(w_i)) \quad \odot \text{ seriality} \\ \vdots \end{array} \right.$$

$\delta$  *reflexivity*

$$\left| \begin{array}{l} \vdots \\ \text{k. } R_{\delta X}(w_i, w_i) \quad \delta \text{ reflexivity} \\ \vdots \end{array} \right.$$

$$\left| \begin{array}{l} \vdots \\ \text{k. } R_{\delta T}(w_i, w_i) \quad \delta \text{ reflexivity} \\ \vdots \end{array} \right.$$

# Proving minimum condition

- Easy part in proof of adequacy of logic for KTR.
  - Construct a proof for each implication from  $RP^{imp}$ .
    - Other implications (gained due to reflexivity and transitivity) are trivial (reiteration and hypothetical syllogism are provable).
- Example: transversal implication.

Example <4.10>.  $\vdash_{O\delta}^{kl} w_0: O\delta_Y\varphi \rightarrow O-\delta_X-\varphi$

1.		
2.	$w_0: O\delta_Y\varphi$	
3.	$R_O(w_0, w_1)$	
4.	$w_1: \delta_Y\varphi$	$O$ Elim: 2, 3
5.	$R_{\delta_Y}(w_1, w_1)$	$\delta$ reflexivity
6.	$w_1: \varphi$	$\delta_Y$ Elim: 4, 5
7.	$w_1: \delta_X-\varphi$	
8.	$R_{\delta_X}(w_1, w_1)$	$\delta$ reflexivity
9.	$w_1: \neg\varphi$	$\delta_X$ Elim: 7, 8
10.	$w_1: \perp$	$\perp$ Intro: 6, 9
11.	$w_1: \neg\delta_X-\varphi$	$\neg$ -Intro: 7-10
12.	$w_0: O-\delta_Y-\varphi$	$O$ Intro: 3-11
13.	$w_0: O\delta_Y\varphi \rightarrow O-\delta_X-\varphi$	$\rightarrow$ -Intro: 2-12

**Example <4.10>**.  $\vdash_{O\delta}^{kl} w_0: O\delta_Y\varphi \rightarrow O\neg\delta_X\neg\varphi$

- |    |     |  |   |
|----|-----|--|---|
| 1. |     |  |   |
|    | 2.  | $w_0: O\delta_Y\varphi$                                      |   |
|    |     | 3.   | $Ro(w_0, w_1)$  |
|    |     | 4.   | $w_1: \delta_Y\varphi$ <span style="float: right;"><math>O</math> Elim: 2, 3</span>             |
|    |     | 5.   | $R_{\delta Y}(w_1, w_1)$ <span style="float: right;"><math>\delta</math> reflexivity</span>     |
|    |     | 6.   | $w_1: \varphi$ <span style="float: right;"><math>\delta_Y</math> Elim: 4, 5</span>              |
|    |     | 7.   | $w_1: \delta_X\neg\varphi$  |
|    |     | 8.   | $R_{\delta X}(w_1, w_1)$ <span style="float: right;"><math>\delta</math> reflexivity</span>     |
|    |     | 9.   | $w_1: \neg\varphi$ <span style="float: right;"><math>\delta_X</math> Elim: 7, 8</span>          |
|    |     | 10.  | $w_1: \perp$ <span style="float: right;"><math>\perp</math> Intro: 6, 9</span>                  |
|    |     | 11.  | $w_1: \neg\delta_X\neg\varphi$ <span style="float: right;"><math>\neg</math> Intro: 7-10</span> |
|    | 12. | $w_0: O\neg\delta_Y\neg\varphi$                              | $O$ Intro: 3-11   |
|    | 13. | $w_0: O\delta_Y\varphi \rightarrow O\neg\delta_X\neg\varphi$ | $\rightarrow$ Intro: 2-12   |

## Harder : proving unprovability

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- All rights-implications not belonging to KTR should be unprovable in LD system.

$U$  is the set of right types.

Logic  $\vdash_l$  satisfies maximum condition iff

for any  $R \in (U \times U - KTR)$  it holds that  $\not\vdash_l R$ .

## Strategy of the proof

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1. Introducing a simple semantics for deontic and praxeological modalities.
2. Proving soundness of LD system.
3. Contraposition: unsatisfiable sentences are unprovable.
4. Construction of counterexamples for each “undesirable” implication.

# The simplest semantics of action

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- Hilpinen attributes the simplest semantics of action to Chellas (1969).
  - “[...] ‘ $a$  sees to it that  $p$ ’ is true in a world  $u$  if and only if  $p$  is true in every alternative to  $u$ . The alternatives to a given world  $u$  are its ‘practical’ alternatives: they are worlds in which agent behaves in the same way as in  $u$ .”

# Simple model

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- Three accessibility relations:
  - one reflexive deontic relation, and two serial praxelological relations (one for each agent).
- Valuation of propositional letters at worlds.
- Additionally: interpretation function for predicates and terms of relational theory.

$R_O$  is serial,  $R_{\delta X}, R_{\delta Y}$  are reflexive.

$$\llbracket R_{\odot} \rrbracket = R_{\odot}, \odot \in \{O, \delta X, \delta Y\}$$

$$\llbracket w \rrbracket \in W, \llbracket f(w) \rrbracket \in \{v : R_O(w, v)\}$$

$$\mathfrak{M} = \langle \langle W, R_O, R_{\delta X}, R_{\delta Y} \rangle, V, \llbracket \cdot \rrbracket \rangle$$

## Standard semantic definitions

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- Separate definitions for sentences of relational theory and for labelled sentences.
  - Examples show generalized modalities.

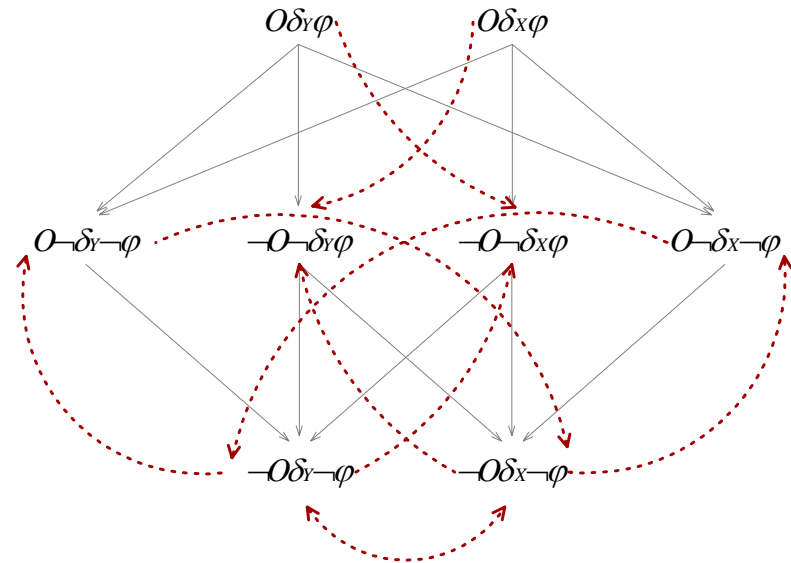
$$\mathfrak{M} \models R_{\circ}(t_1, t_2) \text{ iff } \langle \llbracket t_1 \rrbracket, \llbracket t_2 \rrbracket \rangle \in \llbracket R_{\circ} \rrbracket$$

...

$$\mathfrak{M} \models w : \odot \varphi \text{ iff for all } v : R_{\circ}(\llbracket w \rrbracket, v) \rightarrow \mathfrak{M} \models v : \varphi$$

# Soundness proof and counterexample construction

- 1. Straightforward.
- 2. Laborious [40 counterexamples; reducible to 5 cases].



# Conclusion

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- LD system for KTR meets Segerberg criteria of adequacy.
- [Not discussed] LD system is complete with respect to “the simplest semantics” of action.
  - Modification of standard proof.

$$\Gamma_{i+1} \cup \Delta_{i+1} = \begin{cases} \Gamma_i \cup \Delta_i & \text{if } \Gamma_i \cup \{S_{i+1}\} \cup \Delta_i \vdash u : \perp \text{ for some } u \in I^*, \\ \text{otherwise} & \begin{cases} \Gamma_i \cup \{S_{i+1}\} \cup \Delta_i & \text{if } S_{i+1} \neq w : \neg \odot \varphi, \\ \Gamma_i \cup \{w : \neg \odot \varphi, w_{\neg \odot \varphi} : \neg \varphi\} \cup \Delta_i \cup \{R_{\odot}(w, w_{\neg \odot \varphi})\} & \text{if } S_{i+1} = w : \neg \odot \varphi. \end{cases} \end{cases}$$

Thank you!

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